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Graphics and Composite Material Computer Program Enhancements for SPAR

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# GRAPHICS AND COMPOSITE MATERIAL COMPUTER PROGRAM FOR USE WITH SPAR

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#### SUMMARY

The SPAR computer software system is used for finite element structural and thermal analysis. This report contains user documentation of additional computer programs that have been developed for use in conjunction with SPAR. These programs plot digital data, simplify input for composite material section properties and compute lamina stresses and strains. Sample problems are presented including execution procedures, program input and tabulated and graphical output.

N80-18750#

#### INTRODUCTION

Studies of structural configurations using finite element models yield large amounts of data which must be analyzed. Effective evaluation of these data can be enhanced by a graphical representation. This paper contains the user documentation for computer programs developed or modified to interface with the data base of the SPAR level 14 finite element computer code (reference 1). These capabilities are used in the interpretation of results and in reducing input to the composite material section properties of the SPAR computer code. These capabilities include; (1) a hidden line graphics program for plotting the deformed and undeformed finite element model; (2) a contour plotting program; and (3) a capability for the development of composite material section properties and subsequent postprocessing of lamina stresses and strains into a more convenient form. These programs are written in FORTRAN IV language for the Control Data Cyber series digital computers with the Network Operating System (NOS). The plotting program contains adequate comment statements to allow conversion to any plotting system.

#### SYMBOLS

X Y Z - Coordinate system fixed in model

 $X_0$   $Y_0$   $Z_0$  - Coordinate system containing viewing planes

z - Coordinate through the thickness

σx σy τxy - Normal and shear stresses in the elemental reference frame

ol ol one of the principal of the principal material coordinate systems

 $^{\epsilon}$ x  $^{\epsilon}$ y  $^{\gamma}$ xy - Normal and shear strains in the elemental reference frame

 $^{\epsilon}$  l  $^{\epsilon}$  2  $^{\gamma}$  12  $^{-}$  Normal and shear strains in the principal material coordinate system

Ell E22 E33 - Three dimensional extensional G12 G12 G23 and shear moduli and Poisson's UN12 UN13 UN23 ratio

RHO - Material density

t - Finite element thickness

 $h_i$  - Distance from neutral axis

k - Layer numbers

#### Program Capabilities

The three capabilities described in this report were developed as preprocessors or post processors to SPAR, interacting only with the SPARLA data base. By implementing these capabilities in this fashion the impact on subsequent versions of SPAR would be minimized. The necessary I/O and data handling routines employed in these capabilities are described in reference (2).

Another common feature of these capabilities is dynamic addressing of storage (DAS). By utilizing DAS all problem dependent vectors of data are stored in a single working vector in blank COMMON. This allows the user to specify only the central memory necessary to solve the problem. The working vector, blank COMMON, begins at the first word address following the loaded program and extends to the end of the available central memory as defined by the user.

The concept of element groups and types, in SPAR, can enable a user to greatly reduce the complexity of modeling and interpreting the results of a structure. In a similar fashion the three capabilities utilize this concept to allow the user to specify parts of the structure to be operated upon. This is performed by the selection of sets of element groups and types. No option exists to select specific elements within a particular group.

## HIDDEN LINE REMOVAL GRAPHICS PROGRAM - HIDLIN

The hidden-line graphics program, denoted as HIDLIN, is a modification of that presented in references 3 and 4 which was an option to the general orthographic plotting program of reference 5. Plots of the deformed and undeformed finite element model in a 3-D rectangular Cartesian coordinate system are generated on a 2-D viewing plane by HIDLIN. The deformed plots are of nodal translations such as static displacements and vibration or buckling modes. Such plots are very useful in debugging complex finite element models and in visualizing the overall structural response of the model.

Comparison of figures 1 and 2 illustrates the clarity of a composite cross beam model drawn by HIDLIN versus a drawing of all elements by SPAR. The deformed plot is shown in figure 3.

Another example of the usefulness of HIDLIN is depicted in figures 4 through 7 showing the finite element model used in supersonic cruise aircraft research at NASA - Langley Research Center (ref. 6). This model consists of rods, shear webs and triangular and quadrilateral membrane and aleotropic elements. The full undeformed finite element model of the aircraft model is presented in figure 4 with figures 5 and 6 representing the undeformed and deformed HIDLIN

plots respectively. Figure 7 represents the HIDLIN drawing of just the shear webs of the model depicting the internal structure. Upon inspection of figures 1 through 7 the advantages of using HIDLIN is evident in debugging and visualizing the structural response of the finite element models.

Plots can be generated for structural models containing any combination of 1, 2 and 3-D elements. Faces of the solid elements (3-D) are internally converted by the program to triangular or quadrilateral (2-D) elements for computation purposes. In terms of SPAR nomenclature the elements the user can specify are; E21-E24, E31-E33, E41-E44, S41, S61, S81.

elements" can occur during a normal execution of HIDLIN.

These errors, if they occur, do not greatly detract from the overall appearance of the structure and do not reduce the program's effectiveness in debugging complex finite element models or in depicting overall structural response as seen by comparing figures 3 and 8. To eliminate these errors, the user can rotate the model a few degrees or adjust DMAG. DMAG, used in checking an element's visibility, is the parameter that controls the amount an element is reduced about its center. The causes of these errors are numerical roundoff and a limitation on the number of segments of a partially hidden element.

The additional computation required to reduce or eliminate these errors is not justifiable.

Input data. - The input data deck is shown schematically in Figure 9 and is described in detail in this section.

SPAR data base SPARLA must be disc resident prior to the execution of HIDLIN.

SPARLA data. - The SPARLA data base must contain the basic structure topology prior to execution of HIDLIN.

SPARLA DAT SET NAME	ΓA		DESCRIPTION
JLOC BTAB	2 5		Data set containing nodal
			coordinates
DEFO POSI	MASK	MASK	Data set containing nodal
			translations in similar format
			as JLOC BTAB. This data set
			is used in deformed plots
			only. This data set can be
			developed through use of the
			TRAN function in processor
			AUS.
DEF E21	MASK	MASK	Data sets containing element
	11	н	connectivities.
" E24 " E31		11	
•			
" E33	Ħ	#1	
" E41	11	11	
•			

E44 S41 S61 S81 <u>User defined data</u>. User defined data includes a NAMELIST statement and data defining element type and group numbers of the plotted structure.

NAMELIST MAX. - This NAMELIST contains values to allocate storage and values specifying various program options.

FORTRAN NAME	DEFAULT VALUE	DESCRIPTION
IDISP	0	Deformed plot parameter
		0 - undeformed plot
		1 - deformed plot
NCKELE		Estimate of the total number
		of triangular and quadri-
		lateral finite elements (must
		be equal to or greater than
		the actual numbers)
DSCALE	1.0	Displacement magnification
		factor used when IDISP=1
DELX, DELY	1.0	Origin shift factor in the
		scaled and rotated coordinate
		systems
KHORZ	1	Integer designating the
		horizontal axis of the
		<pre>viewing plane where l=X<sub>o</sub>;</pre>
		$2=Y_{0}; 3=Z_{0}$
KVERT	2	Integer designating the
		vertical axis of the viewing
		plane where $1=X_0$ ; $2=Y_0$ ; $3=Z_0$

FORTRAN NAME	DEFAULT VALUE	DESCRIPTION
PHI	0.0	Angular rotation of model about
		its X-axis in degrees (per-
		formed third)
THETA	0.0	Angular rotation of model
		about Y-axis in degrees
		(performed second)
PSI	0.0	Angular rotation of model
		about its Z-axis in degrees
		(performed first)
PSCALE	1.0	Joint coordinate magnification
		factor
DMAG	.99	Reduction factor used in
		reducing the size of each
		element about its center for
		checking visibility of an
		element.

The scaling of the joint coordinates (XYZ) and deformations (DISP) and the translation of the plotting origin (DELX, DELY) is described by the following equation;

original

XYZ<sup>plot</sup> = XYZ model \* PSCALE + DISP \* DSCALE + DEL(X or Y).

The following card(s) determine element type and group number to be considered by the program.

## COLUMN FORTRAN VARIABLE

1-5	(Right	adjusted)	NGRP	Element group number
6-10	) "		NELT	Spar Element Type
			21	E21
			22 • 44	E22 : E44
			441	S41
			661	S61
			881	S81

An estimate of the field length required to run HIDLIN is given as follows:

 ${
m FL}_{10}$  = 18355 + 6\* (NNOD + NCKELE) where NNOD is the number of nodes and NCKELE is the sum of the triangular and quadrilateral finite elements.

Output. The input NAMELIST MAX is printed to verify input data, followed by the length of blank common required for program execution. The third section of output is a listing of element types and group numbers that are being plotted. An example of input and output (printed and plotted) is presented in sample problem 1.

#### CONTOUR PLOTTING

The contour plotting capability consists of two programs which are executed sequentially. The first program, denoted as STR, extracts user designated topology and stress

information from the SPARLA library and sets up two input files for the contour plotting program, STCR. Using the input data developed by STR, STCR plots contours over the specified structure. Besides the contour levels only the border of the specified structure is drawn to reduce confusion. Three plots are generated corresponding to  $\sigma_{\rm X}$ ,  $\sigma_{\rm Y}$ , and  $\tau_{\rm XY}$  stresses. Figure 10 depicts stress contours of the upper flange of the composite cross beam structure shown in figures 1 through 3.

#### PREPROCESSOR FOR CONTOUR PLOTTING - STR

STR extracts stress and topology data resident in the SPARLA library and sets up two input files for the contour plotting program STCR. The user designates the element types and group numbers in specifying the desired structure. Triangular and quadrilateral membrane and aleotropic elements are considered in SPAR nomenclature as E31, E33, E41, E43 elements. All the elements in the specific groups are included in the input file for STCR.

Stresses as calculated in SPAR are oriented in the local elemental reference frame. These local reference frames can vary from element to element and must be transformed to a common reference frame. This transformation is accomplished by rotating these local stresses by the angle  $\theta$  which the user must input into the SPAR material property (MATC) table.

Input data. The input data deck is shown schematically in Figure 9 and is described in detail in this section. SPAR data base SPARLA must be disk resident prior to the execution of STR.

SPARLA data. - The SPARLA data base must contain the basic structure topology and stress information prior to execution of STR.

SPARLA DATA SET NAME	DESCRIPTION
JLOC BTAB 2 5	Data set containing nodal
	coordinates
MATC BTAB MASK MASK	Data set containing material
	property table
SA BTAB MASK MASK	Data set containing section
	property table
STRS E31 MASK MASK " E33 " "	Data sets containing element
" E41 " " " E43 " "	connectivities and stress
747	information

User defined data. User defined data includes a NAMELIST statement and data defining element type and group numbers of the plotted structure.

NAMELIST MAN. - This NAMELIST contains topology and stress parameters pertinent to the execution of STR. MAN also contains the appropriate NAMELIST parameters used in NAMELIST MAX of program STCR.

FORTRAN NAME	DEFAULT VALUE	DESCRIPTION
III	1	Horizontal axis on viewing plane
		where $1=X$ , $2=Y$ , $3=Z$ are the
		model coordinate system
JJJ	2	Vertical axis on viewing plane
		where $l=X$ , $2=Y$ , $3=Z$ are the
		model coordinate system
IPOS	0	Location of stress calculation
		for SPAR finite elements
		0   z = 0   (mid-plane)
		6 $z = t/2$ (upper-surface)
		12 $z = -t/2$ (lower-surface)
ICEN	0	Location of stress component
		(this parameter common to STR
		and STCR)
		0 centroidal stress
		1 nodal stress

The following parameters are required in this NAMELIST and are passed to program STCR.

SCLX, SCLY	1.0	Joint coordinate scale factor
XSHFT, YSHFT	1.0	Origin shift factor
NCONT	5	Number of contour levels
ILAB	0	Contour labeling parameter
		0 - No
		1 - Yes
HGHT	.1	Size of contour label

FORTRAN NAME	DEFAULT VALUE	DESCRIPTION
ICOPT	0	Contour specification parameter
		0 - program specifies contour
		based upon the formula
		$SS(J) = \frac{(I)}{NCONT+1} * (SMAX(J)-SMIN(J))$
		+ SMIN(J)
		I=1, NCONT; J=1, 2, 3
		Where SS is the stress contour
		level and J=1, 2, 3 represents
		the stress component $\sigma_{x}$ , $\sigma_{y}$ , $\tau_{xy}$ ,
		respectively
		1 - user specifies contour
		levels based upon the formula
		SS(J) = (I-1) * DSIG(J) + SIG(J)
SIG(J)	0.0	Starting stress contour level
DSIG(J)	0.0	Stress contour level increment
RNDOFF	1.0E-7	Roundoff error parameter
		used to eliminate small
		deviations from 0.0 level contour
ILEROY	0	Leroy plotting option
		0 - No
		1 - Yes

The following card(s) determine element type and group number to be considered in this program.

#### COLUMN

#### FORTRAN VARIABLE

	<del></del>					
1-5	(Right	adjusted)	NN	Element	type	
			-	Spar Ele	ement	NN
				E31		31
				E33		33
				E41		41
				E43		43
6-10	(Right	adjusted)	NG1	Element Number	Group	

The user can stack several different type and group cards to define the appropriate structure.

An estimate of the field length required to run STR is given as follows:

where NNN = 
$$9$$
 if ICEN =  $0$ 
 $16$ 

NNOD is the number of nodes in the model, NMAT and NSECT are the number of entries in the MATC and SA tables respectively, NEL is the number of finite elements to be plotted and ICEN defines where the stresses are computed on the elements.

Output. - The output from this program is in two forms, printed and disk or tape resident. Input NAMELIST MAN is printed to verify input data, followed by the length of blank common required for program execution. The third section of output is a listing of the element types and group numbers that are to be plotted. The disk resident output from this routine to be used in the contour plotter is formatted in card

images and located on tape 9 and tape 10. The data structure of tape 9 consists of; NAMELIST MAX, sequential ordering of joints and element connectivities. Tape 10 contains the elemental centroidal or nodal stresses  $(\sigma_{\mathbf{x}}, \sigma_{\mathbf{y}}, \tau_{\mathbf{xy}})$ .

## CONTOUR PLOTTING PROGRAM - STCR

The contour plotting program, STCR, draws the border of the specified structure along with specified contour levels. Those contours intersecting the border can be optionally labeled corresponding to the printed output. The contour levels are tabulated in the program output. The method of drawing contours employed in STCR is analogous to that of reference 5 and will not be discussed here. Three contour plots, depicting  $\sigma_{\mathbf{x}}$ ,  $\sigma_{\mathbf{y}}$ , and  $\tau_{\mathbf{xy}}$ , are drawn during a program execution as demonstrated in sample problem 2.

The contours depicted in figures 10a through 10c have sharp corners and small extensions which could mislead the interpretation of results by a novice user of a finite element program. These corners are a result of the stress averaging at the element nodes and calculation of the contour line segment. These contours can be made smoother by using a finer mesh of elements.

Input data. - If program STCR is executed sequentially after STR, no additional input is necessary. The following data are given to allow this program to be used alone. Tape 9

(input file) contains NAMELIST MAX, sequential ordering of joints and element connectivities while tape 10 contains element centroidal or nodal stresses ( $\sigma_{x}$ ,  $\sigma_{y}$ ,  $\tau_{xy}$ ).

NAMELIST MAX. - This NAMELIST contains all the parameters necessary to control the contour plotting.

FORTRAN DEFAULT VALUE

NNOD Number of nodes

NEL Number of elements

See NAMELIST MAX of program STR for description of the following: SCLX, SCLY, XSHFT, YSHFT, NCONT, ILAB, HGHT, ICOPT, SIG(3), DSIG(3), RNDOFF, ILEROY.

·Sequential ordering of nodal coordinates

$$X_C$$
,  $Y_C$ ; (NNOD cards) (2F10.4)

- •Element Connectivities (NEL cards) (415)
- ·Element centroidal or nodal stresses

$$\sigma_{x}$$
,  $\sigma_{y}$ ,  $\tau_{xy}$  (3F10.4)

if ICEN=1 nodal stresses

$$\sigma_{\mathbf{y}}$$
 (4F10.4)

$$\sigma_{v}$$
 (4F10.4)

An estimate of the field length required to run STCR is given as follows:

$${
m FL}_{10}$$
 = 18088 + 6\* NNOD + 4\* NEL where NNOD and NEL are the number of nodes and finite

elements respectively.

Output. - NAMELIST MAX is printed to verify input. The length of blank common is indicated. The contour number and its associated value is listed. A typical plotted output is shown in sample problem 2.

#### COMPOSITE LAMINATE CAPABILITY

The composite laminate program consists of two programs; SAT, which is used to calculate the section property table (SA data set), and program STST for the determination of lamina stresses and strains in the elemental and principal material directions. The input of composite laminate section properties into SPAR is possible by direct input of the laminate stiffness coefficient matrix or by ply-by-ply specification of the lamina stiffness matrix. Either method requires the user to execute additional programs, separate from SPAR, to generate this input data. In the execution of program SAT the user defines the necessary orthotropic material properties and the appropriate stacking sequence for each section while the program performs all necessary calculations for the SPAR SA table entries.

The stress recovery in SPAR has two forms. For all elements with section types other than LAMINATE the laminate stress resultants or average laminate stresses are computed while the LAMINATE section type provides for the calculation of stresses on a ply-by-ply basis only. Neither of these allow for the direct determination of strains in the elemental

or principal material reference direction. In addition to the SPAR generated stress data the user can have program STST calculate stresses and strains in the elemental and principal material directions on a ply-by-ply basis. This information can be optionally directed to a file in a format consistent with input for the contour plotting program STCR.

#### SHELL SECTION PROPERTIES PROGRAM - SAT

The SAT program generates shell section properties, SA table entries, applicable to composite materials. Besides the SA table data set, developed by SAT, a data set containing constituent section properties, denoted as ARMY COMP (NLAY) 0, is stored in the SPARLA library. These data sets in addition to the stress resultants computed by SPAR are used by program STST in computing lamina stresses and strains of the appropriate elements. The SA tables generated by SAT are applicable to the following SA sections; isotropic, membrane, plate, uncoupled and coupled.

The user specifies the constituent material properties to be used in developing all the different section properties. Each different section is defined with respect to ply orientation, lamina thickness and constituent materials. Sign convention and consistency with the mathematical formulation of SPAR is maintained. Figure 11 depicts sign convention and typical laminate construction.

Input data. - The input data deck is shown schematically in figure 12 and is described in detail in this section.

SPAR library SPARLA must be disk resident prior to the execution of SAT.

Comment card. - One card required to identify the data deck.

NAMELIST MAX. - This NAMELIST sets up the required number of cards to be read later for different section properties. Note, there are no default values in this namelist.

FORTRAN	VARIABLE
TOTATION	A 7 7 1 ( T 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7

### DESCRIPTION

NSECT Number of different section properties to be developed

NLAY Maximum number of layers in

a section

NMAT Number of different material properties to be input

NAMELIST PROP. - This NAMELIST contains the material identification number and its associated properties.

#### FORTRAN VARIABLE

UN12, UN13, UN23

RHO

#### DESCRIPTION

IMAT Material property identification

(number not to exceed NMAT)

E11, E22, E33, Three dimensional material G12, G13, G23,

properties

Material density

NAMELIST SECT. - This NAMELIST contains the section topology information to be read in NSECT times.

FORTRAN VARIABLE	DESC	CRIPTION
ILAY	Number of	layers in section
ISPARM	SPAR mater	rial number
	correspond	ling to MATC table
	entry	
ISPTYP	SPAR secti	on type
	ISPTYP S	PAR SECTION TYPE
	1	membrane
	2	plate
	3	uncoupled
	4	coupled
	3	isotropic

ZSHFT

Neutral axis shift

The following layer identification card(s) to be read ILAY times for each section.

COLUMN	FORTRAN VARIABLE	DESCRIPTION		
1-10	THETA(I)	lamina rotation angle,		
		relative to the elemental		
		and material coordinate systems,		
		refer to figure ll(b)		
11-20	T(I)	lamina thickness		
21-25 (Ri adjus		lamina material number (IMAT)		

SPAR stress recovery cards

#### FORTRAN VARIABLE

#### DESCRIPTION

F(I, J)

SPAR stress recovery parameter I=1, 2, 3; J=1, 2, 3, 4, 5, 6
(18 entries) Format (8E10.3)

An estimate of the field length required to run SAT is given as follows:

 ${
m FL}_{10}$  = 18867 + 37\* NMAT + (12\* NLAY+140) \* NSECT + NLAY where NMAT is the number of different materials, NLAY is the maximum number of layers in any laminate and NSECT is the number of sections (SA table entries).

Output. - All input NAMELISTS are printed along with the [ABD] matrices (a 6 x 6 laminate coefficient stiffness matrix) and their inverses for each section (SA table entry). An example of input and output is presented in sample problem 3.

## STRESS-STRAIN CALCULATION PROGRAM - STST

Program STST determines lamina stresses and strains in the elemental and principal material directions. A contour plotting option is available to the user in the creation of a stress or strain file applicable to program STCR. As was the case in programs HIDLIN and STR the user defines the structure of interest by specifying group numbers and element types. All the elements within such a specification would have their lamina stresses and strains computed. Successive specifications can be defined to establish the desired structure.

Input data. The input data deck is shown schematically in Figure 9 and is described in detail in this section.

SPAR library SPARLA must be disc resident prior to execution with data set ARMY COMP (NLAY) 0, generated by program SAT, resident.

SPARLA data. The SPARLA data base must contain the constituent material properties for each section, as generated by SAT, and stress information prior to the execution of STST.

SPARLA DATA SET NAME	DESCRIPTION
ARMY COMP (NLAY) 0	Data set containing the consti-
	tuent material properties for
	each section
STRS E31 MASK MASK " E33 " "	Data set containing element
" E41 " " " E43 " "	stress information
MATC BTAB MASK MASK	Data set containing material
	property table

<u>User defined data.</u> User defined data includes a NAMELIST statement and data defining element type and group numbers of the plotted structure.

NAMELIST MAX.-

FORTRAN VARIABLE	DEFAULT	DESCRIPTION	
IPLAY	1	Layer number for plotting	
IGRPH	0	Plotting parameter	
		No = 0	
		Yes = $1 \equiv \sigma_{x}, \sigma_{y}, \tau_{xy}$	
		$2 \equiv \epsilon_{x}, \epsilon_{y}, \gamma_{xy}$	

FORTRAN VARIABLE	ORTRAN VARIABLE DEFAULT DESCRIPT	
		$3 \equiv \sigma_1, \sigma_2, \tau_{12}$
		$4 \equiv \epsilon_1, \epsilon_2, \gamma_{12}$
PER	.5	Ratio defining where the
		stresses, thoughthe thickness,
		in each layer are computed.
		PER is relative to the lower edge
		of each lamina. NOTE: PER = .5
		is mid-surface

The following card(s) indicate the element type group number to be considered by the program.

COLUMN		FORTRAN VARIABLE		DESCRIPTION			
1-5 (Right adjusted)		NELE	Elemen	Element type			
	, ,		NELE S	SPAR ELEMENT TYPE			
			31	E31			
			33	E33			
			41	E41			
			43	E43			
6-10	(Right adjusted)	NGRP	Element	t group number			

An estimate of the field length required to run STST is given as follows:

 ${\rm FL}_{10} = 24249 + 24*\ {\rm NMAT} + {\rm NSECT}^*\ (11*\ {\rm NLAY} + 44)$  where NMAT is the number of different materials, NSECT is the number of sections (SA table entries) and NLAY is the maximum number of layers in any laminate.

Output. - The input NAMELIST MAX is printed out along with information pertaining to laminate construction generated by SAT. For each element of the specified group and type the laminate strains and curvatures and lamina stresses and strains in the elemental and principal material directions are printed. Stresses or strains for designated layers are printed on tape 10 for use in conjunction with program STCR. An example of input and output is presented in the sample problem 4.

#### Concluding Remarks

The computer codes described in this report have been found to reduce hand manipulation of data and improve visualization of results. The HIDLIN program proved beneficial in debugging complex finite element models and visualizing the overall response of the model. The composite material programs SAT and STST greatly reduce the manipulation of input data and extend the computational capability of SPAR. The contour plotting program used in conjunction with SPAR or program STST significantly adds to the stress plotting capabilities currently available in SPAR.

#### REFERENCES

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- 3. Farley, Gary L.: Interactive Structural Optimization With Strength and Flutter Constraints. M.S. Thesis, The George Washington University, 1976.
- 4. Farley, Gary L.: Three Dimension Hidden Line Plotting Algorithm with Contour Capabilities. VPI-E-77-9, 1977.
- 5. Giles, Gary L.: Digital Computer Programs for Generating Oblique Orthographic Projections and Contour Plots. NASA TN D-7797, 1975.
- 6. Giles, Gary L.; and McCullers, L. A.: Simultaneous Calculation of Aircraft Design Loads and Structural Member Sizes. AIAA Preprint No. 75-965, August 1975.

#### SAMPLE PROBLEMS

#### Problem 1

This example illustrates the input, output, and typical plot from program HIDLIN. The Calcomp plotter with Leroy pen was utilized to plot figure 2. A listing of input data cards follows:

* W W X	PHT=-45	,THETA=+45.,PSI=	45. NCKELE=450	, IDISP=0, DSCAL	E=100.,ILERO	Y=15END
1	43					
5	43					
3	43					
4	43					
5	43			*******		can be a second
6	43					
7	43					
A	43					
9	43					
10	43					
16	43					
11	43		-			
12	43					
13	43					
14	43			·		
15	43					
17	. 43				*	
18	43		TO MAKE A SALE MAKE METERS TO THE TAX AND THE TAX	**************************************		
1,7	33					
1	33					
2	33					

The output listing for Problem 1 follows.

```
₹MAX
```

1015P = 1.

NCKFLE = 450.

DSCALF = .1F+03.

DELX = .1E + 01.

DE(Y = .1E+01.

KHOR7 = 1.

KVERT = 2.

PHI = -.45F+02,

THETA = .45t +02.

 $PSI = .45E + 0.2 \cdot$ 

PSCALF = .1E+01.

0MAG = .99F + 00.

ILEROY = 1.

#### 4END

STORAGE REQUIRED IN COMMON (DEC.) 3910 STORAGE REQUIRED IN COMMON (OCT.)00007506

GROUP NUMBER= 1 ELEMENT TYPE= 43 GPOUP NUMBER= - 5 FLEMENT TYPE= 43 GROUP NUMBER= 3 ELEMENT TYPE= 43 GROUP NUMBER= 4 FLEMENT TYPE= 43 GPOUP NUMPER= 5 FIEMENT TYPE= 43 "ID NUMBER= 6 GHILL 33 ELEMENT TYPE= GROUP NUMBER= 2

#### Problem 2

This example illustrates the input and output data from programs STR and STCR. A Calcomp plotter with Leroy pen was utilized to plot (figure 10) the stress contours on the upper flange of a composite cross beam. A listing of input data cards follows:

\$MAN | III = 1.JJJ = 3.NCONT = 20.ILAB = 1.ICOPT = 1.SIG(1) = -4500.SIG(2) = -4000.ILEROY = 1.SIG(3) = -1000.DSIG(1) = 500.DSIG(2) = 500.DSIG(3) = 200.ICEN = 0.SCLX = .5.SCLY =

```
The output listing for program STR of Sample Problem 2
 is shown below.
9 A4 A A
1 ] [
     = 1.
JUJ
       = 3,
SCLX = .5F+00.
SCI Y = .FE+00.
XSHFT
      = .1F+c].
YSHET
       = .1f+01.
TOFN
      = (1.
r corit
       = 20,
THUC
       = 0.
11.04:
       = 1.
10 (SEIT
       = .16+00.
ICOPT
       = ].
514
       = -.45F+04 + -.4F+04 + -.1E+04 +
USTA = .5E+03. .5F+03. .2E+03.
THEFOY = 1,
9 FMD
STORAGE USED IN COMMON + 7 OF 16 X MEL (DEC.)
STORAGE USED IN COMMON + 7 OR 20 X NEL (OCT.) 00004417
FIRMENT TYPE=
                47
GROUP FUMBERS
                6
FIENENT TYPE=
                43
GROUP MUMPERS
                7
FIFMENT TYPE=
                43
```

POUND FIMPEDS

FIRMENT TYPE=

GEOTIB MINNELT

FIFBFNT TYPF=

34

43

14

33

The output listing for program STCR of Sample Problem 2 is shown below.

```
4 MAY
5.000
      = 403.
NFT.
       = 76.
TOPM = 0.
XSHFT = .1E+01.
YSHET
       = .1t+01,
SCI x = .56+00.
5 CT Y = .5E+00.
NOOMT
       = 20.
ILAP = 1.
9687 = .16 + 00.
STG
      = -.45F+04. -.4F+04. -.1E+04.
L & LU
      = .EF+03. .5F+03. .2F+03.
TCO^{r_0}T = 1.
ILEBOY = ].
YMPOFF = .1F-06.
2500
STOPAGE HISED IN COMMON (DEC.) 2723
STORAGE USED IN COMMON (OCT.) 00005243
MAX-MIN STRESS VALUES
          .647F+03 -.748F+04
          .FF2F+04 -.583F+03
          .679F+03 -.678F+03
STUFSS
                  CONTOUR NUMBER 1 VALUE -- 4500000E+04
                                            4000000E+04
 STUFGE
                       July Summer 2 VALHE ---
 STAFSC
                  CONTOUR NUMBER 3 VALUE -- COODOOUL
                  CONTAUP NUMBER 4 VALUE -- 4000000E+03
 STEFSS
          3
```

#### Problem 3

This example illustrates the input and output from program SAT which computes the SA Table entries for SPARLA.

#### A listing of input data cards follows:

```
SAMPLE CASE FOR PROGRAM SAT
MAX NSECT=2.NLAY=6.NMAT=2 SEND
$PPOP IMAT=1,F11=17.F6.E22=2.E6.G12=.52E6.UN12=.38 $END
*PROP IMAT=2,E11=9.E6.E22=9.E6.G12=.6E6.UN12=.3 $END
SSECT ILAY=4. ISPAPM=1. ISPTYP=4 SEND
      .0455
  -45.
  -45.
   45.
   1.0
*SFCT ILAY=5.ISPARM=3.ISPTYP=4 $END
   0.0 .033 1
45. .026 2
0.0 .044 1
45. .026 2
      0.0
   1.0
   1.0
   0.0
```

#### The output listing for program SAT of Sample Problem 3

#### is shown below. NSFOT NURY 1557 STOCKE USED IN COMMON (DEC.) .... ROS. STORAGE USED IN COMMON (OCT.) 0000077) 400 E33 F22 615 -1705+02 ... .. 200E+07 \_\_0. . 1 .000E+07 1110 0.49 4- 5 T 11113 ESMU . Bandar + Ao 0. 0. . none of end 0. 0, of the second second second second KKEPT TLAY ISPADU = 1. TSPTYP = 4% THICKNESS THETE MAT 10-7224. 50+7024. -4507-02 -455F-01 2 -4507-02 -455F-01 2 -4507-02 -455F-01 2 -100E+01 .100E+01 .100E+01 -100E+01 .100E+01 .00E+01 .11/41 .lateagos -71 -2104063F-32 719040E-18 - 5120870F- 1A THUTBER OF AND MATHER FOR SECTION - 47873748 - 11 - 404748 - 41 - 418748 -3273710F-06 -3273710F-06 -3273710F-06 -3273710F-07 -3273710F-06 -3273710F-07 -3273 LECHO OF SA TAPLE

## Problem 4

This example illustrates the input and output of program .

STST lamina stress and strains. This example uses the file

ARMY COMP (NLAY) 0 from problem 3. A listing of input data

cards follows:

```
and legan teacht
```

## The output listing for program STST of Sample Problem 4

is shown below.

\$MAX

IPLAY = 1.

.0 m Hqq91

PER = 0.0.

SEND

MUMBER OF MATERIALS = 3 MAXIMUM NUMBER OF LAYERS/SECTION = 20 NUMBER OF SA TABLE ENTREES = 23

STORAGE USED IN COMMON (DEC.) 6145 STORAGE USED IN COMMON (OCT.)00014001

ម្រប់ពី២ រ	NUMBER	1 ELF	MENT TYPE ?	73.2								
IO FK	SGX	EPX	5G1	មួយរួ	SAY	EPY	562	EP2	TAUXY	GMXY	TAU12	GM12
					_	_						
MID-BEWN			48E-03 870			CURVATURES	• 21	90E-02 -	.157E-02 -	.678E-03		
1 1	-57.	•00051	-10777			00063	-57.	.00021	314.	.00060	-314.	00060
1 2	3726.	.00024	3724.			00065	-1133.	00065	310.	.00060	310.	.00060
1 3	98.	.00031	-11598			00068	98.	.00031	303.	.00058	<b>~303</b> .	00058
1 4	5341.	.00034	5341.			00070	-1165.	-,00070	299.	.00057	299.	.00057
1 5	201.	.00037	-12145	- abs 672	-12145.	00072	201.	.00037	295.	.00057		00057
1 6	6955	.00044	5955.	# 13 th 21 to th	-139A.	00075		00075	287.	.00055		.00055
1 7	25 A	.00047	-12965	.09577	-12765.	00077	356.	.00047	283.	.00054		00054
1 8	RO32.	•00050	8032.	.00050	-1017.	00079		00079	279.	.00054		.00054
1 9	511.	.00056	-13785	58000.		00082		.00056	272.	.00052		00052
1 10	-709.	.00060	212.	air-039		00084		00064	1782.	.00051		00143
1 11	-197.	.00073	-2855, -	.00058	-2163.	00091		.00039	1675.	.00048	983.	.00164
1 12	315.	.00096	-2.558			00098		.00039	1568.	.00045		.00184
1 13	876	.00099	1061.			00105		00045	1461.	.00042		00204
			• • • • •		04.74	• • • • • • • • • • • • • • • • • • • •	- 20114		1401.	*0110-2	-1551.	90204
MIG-PLANE	STRAINS	. 66	85-03879	F-13	498F=03	CURVATURES	.20	90F-02 -	157F-02	.678F-03		
2 1	····7.	.00021	-10777	. C 1043	-10777.	00063		.00021		00060	314	.00050
2 3	3706.	.00024	3726.	.00024		00065		00065		00060		60060
2 3	ရစ္ "	.00031	w11599. w			00068		.00031		00058		.00058
ن ج	5341.	.00034	5341.			00070		00070		00057		
۽ ڏ	201.	.00037	-12145			00072		.00037		00057		00057
2 6	(056	.00044	6955			00075		00075				.00057
2 7	354	.00047	-12955		-12965.			.00047		~.00055		90055
A	6032.	.00050		.00050		00079				00054	283.	
.,	511.	•00056	=13785. =					00079		00054		22054
	700					00082		.00056	-777			
14	97	.00060	-3351			00084	212.	•00039				
14	47.	.00073		.05039		00091	-2855.	-			<b>'19</b>	· · · ·
14 4		ARD10.		.00039		00098				00198	-27.	00005
14 5	_	~00	-1862	.00045	-1627	· -				00192	10.	S0000.
14 6	5740.							.00209	-6704.	~.00186	6.	.00001
14 7		0 b						00158		00175	-30.	00007
14 9		00022	1 /			.00053		.00188		00169	55.	•00010
14 9		00027	1/424.		11524.	.00052		00151	-8494.	00163	-71.	00014
14 10		000039	-11854		-2870.	.00049		•00156	-6181.	00151	103.	.00020
14 11		PE000		*00053	298.	.0004B		00004	-648.	00145		00163
14 12		00049	1492		1700.	.00043	-992.		-376.	00121	853.	.00142
14 13				20000	1119.	.00038		00013	-105.	00097		.00121
14 13	-30AC*	<b>→.</b> 00059	-3A19	00031	530.	.00033	453.	.00005	166.	00073		00100
MID-PLAN	FISTRATES		08-03 .264	£ 43	2126-22							
15 1	-16586.		#95, 20=301 PRPAS-	€∸03 . • 55333	-7501.	CURVATURES			758F-03 -			
څ ۱۴		00014		.00351	19742.	46900		.00359	14036.	.00359	391.	.00075
15 3	-16760.		-25869		-7 24 1.	.00037		00327	15503.	.00352	-374.	00072
15 4		00018		7003 <b>5</b> 6	18199	-00035 00035		.00334	13384.	.00336		.00065
15 5	-15842.		-25123		-7067	.00035		00309	14347.	,0032B	-323.	00062
15 6		00023		.00301	16656	.00034		.00317	12949.	.00320	305.	.0005 <b>9</b>
15 7	-15216.		~24004		-6806	.00032		00291	13190.	.00305		00052
15 B		00026		- 65706. - 48506.	15628	\$6000.	1981.	.00292	12296.	.00297		.00549
15 9	-14500		-22085		****** *******	.00031		00279	12419.	.00289		00r46
15 10		00031	-1381			-00029		.00267	11643.	.00274	203.	•90039
15 11		00037		.00045	-752.	.10028	1088.	•00065	1945.	•00255	-1620.	00270
15 12		00043		.00045	+092.	-00025		00057	1618.	.00234	1445.	.00241
15 13		00049			-1232.	.00021		00050	1292.	.00202	1269.	.00211
1 . 13	-1 .34 °	-,00049	-1835, -	** 3 C O 4 d	-1472.	•00018	-2196.	.00011	966.	.00169		00182

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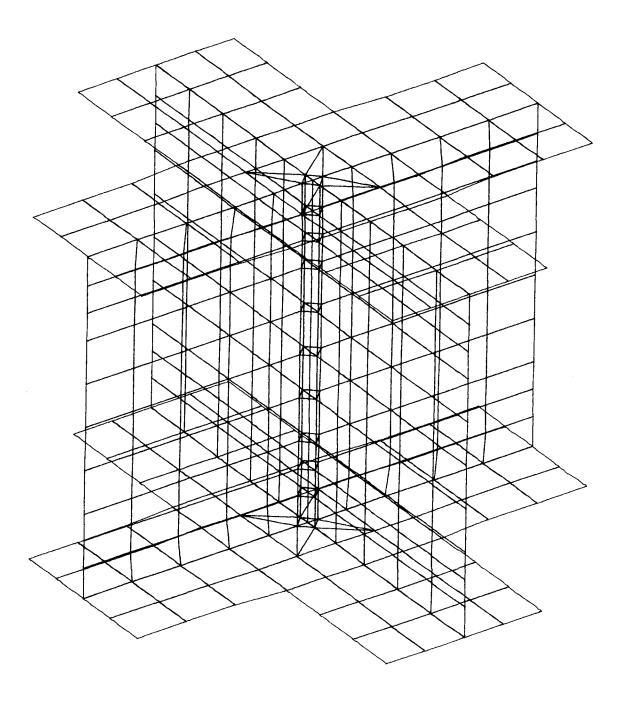


Figure (1).- Composite Cross Beam Finite Element Model, Drawn Using SPAR.

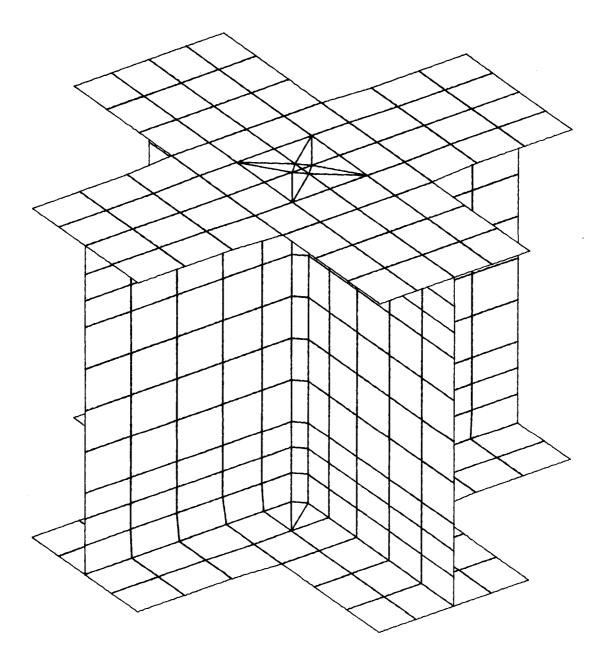


Figure (2).- Undeformed Composite Cross Beam Finite Element Model With Hidden Lines Removed, Drawn Using HIDLIN.

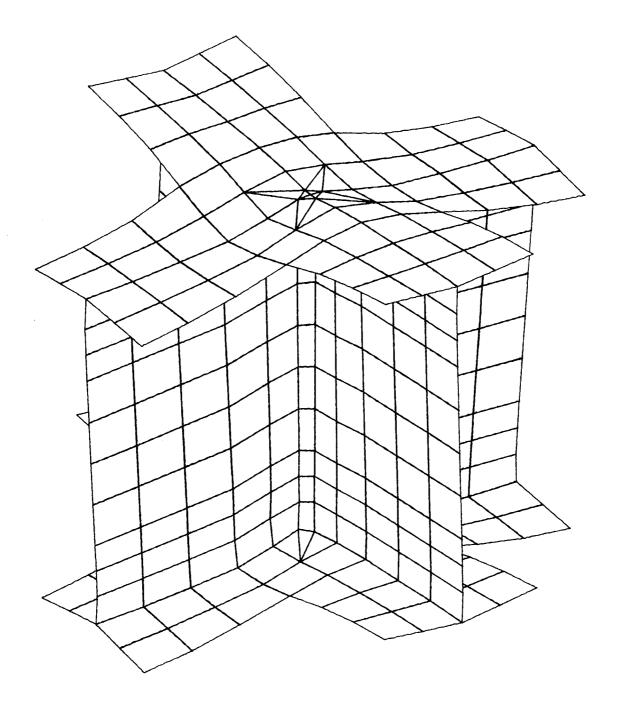


Figure (3).- Deformed Composite Cross Beam Finite Element Model with Hidden Lines Removed, Drawn Using HIDLIN.

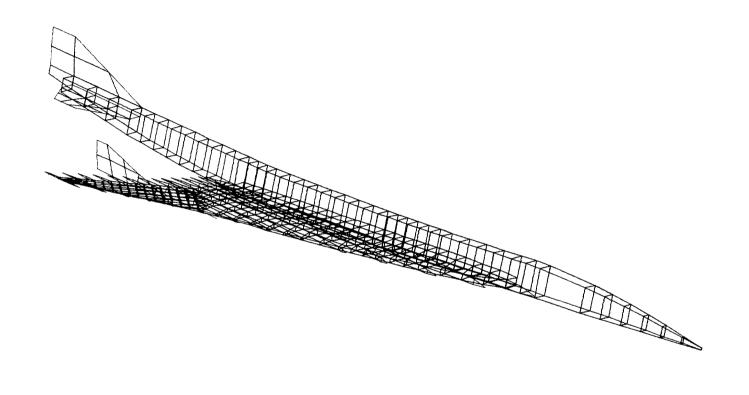


Figure (4).- Finite Element Model of Supersonic Cruise Aircraft, Drawn Using SPAR.

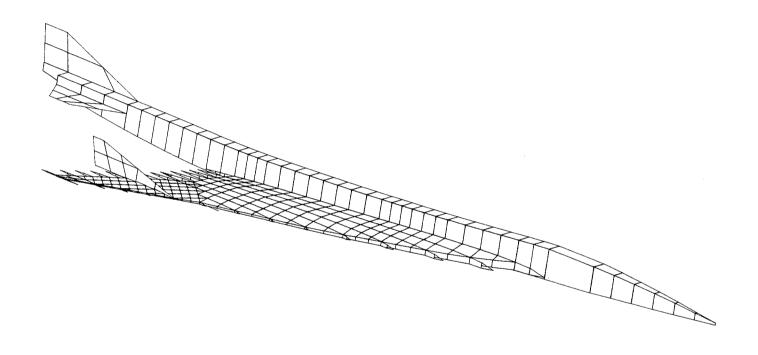


Figure (5).- Undeformed Finite Element Model of Supersonic Cruise Aircraft, Drawn Using HIDLIN.

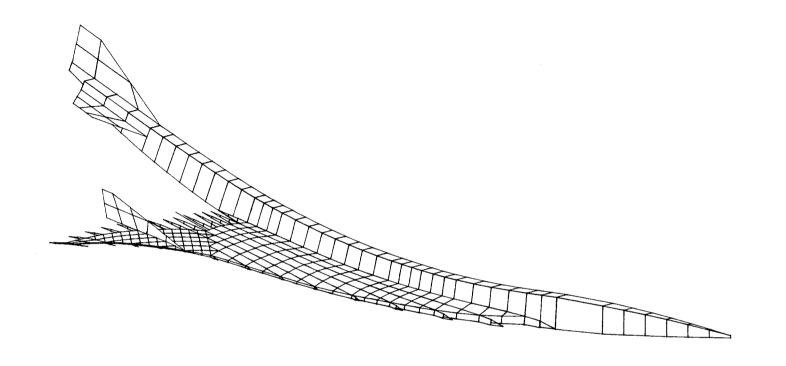


Figure (6).- Deformed Finite Element Model of Supersonic Cruise Aircraft, Drawn Using HIDLIN.

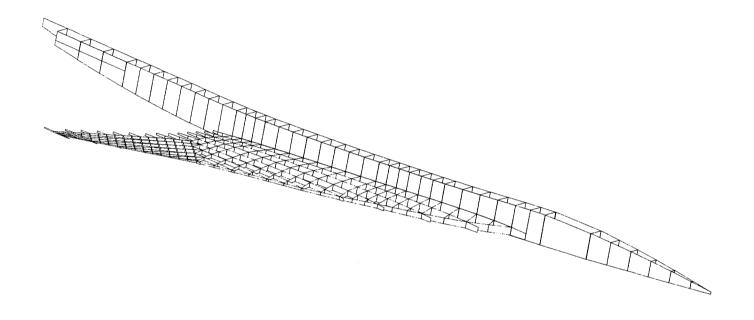


Figure (7).- Internal Finite Element Structure of Supersonic Cruise Aircraft, Drawn Using HIDLIN.

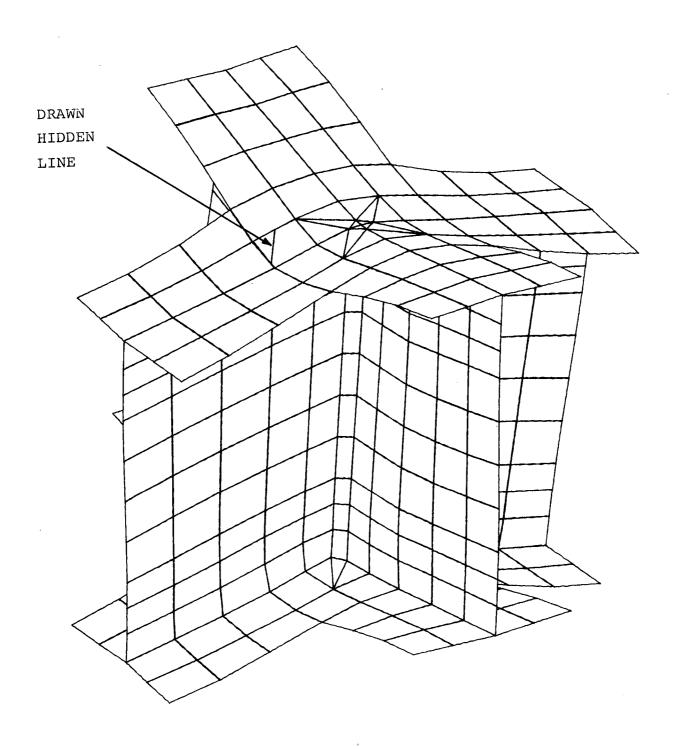


Figure (8).- Composite Cross Beam Finite Element Model With Most of The Hidden Lines Removed, Drawn Using HIDLIN.

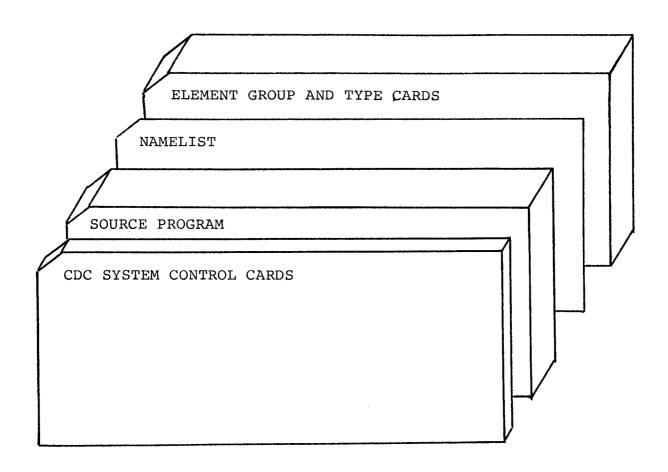


Figure (9).- Typical Program Setup.

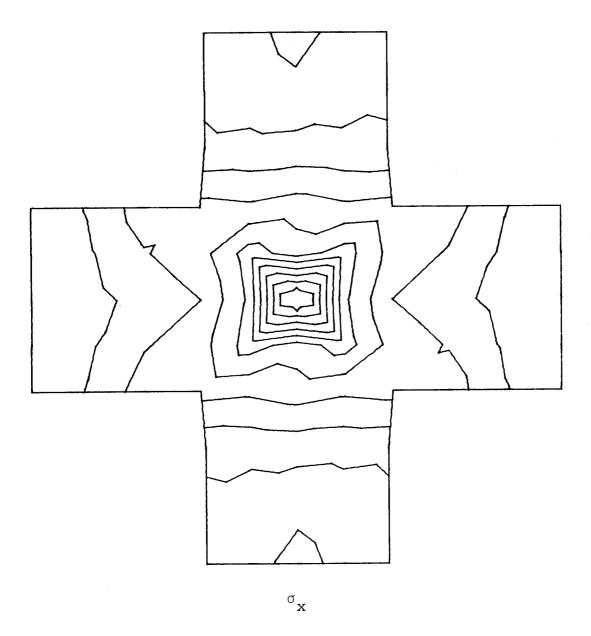


Figure (10a).-  $\sigma_{\mathbf{X}}$  Stress Contours of Upper Flange of Composite Cross Beam Structure.

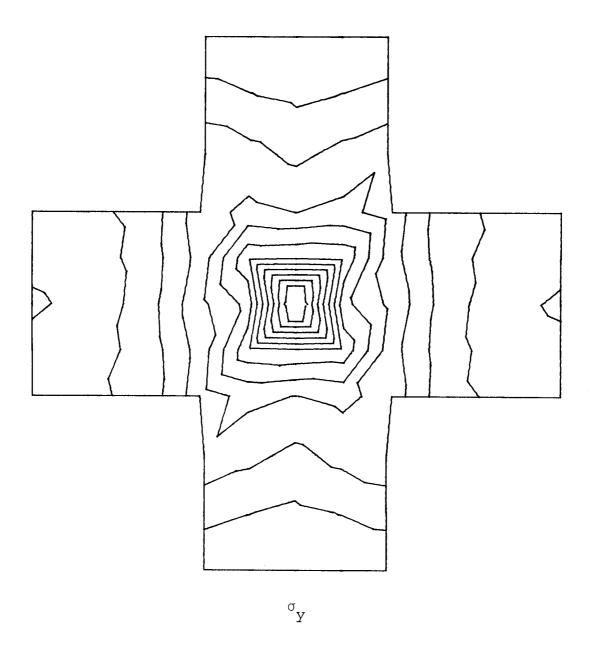


Figure (10b).-  $\sigma_{_{\mbox{\scriptsize Y}}}$  Stress Contours of Upper Flange of Composite Cross Beam Structure.

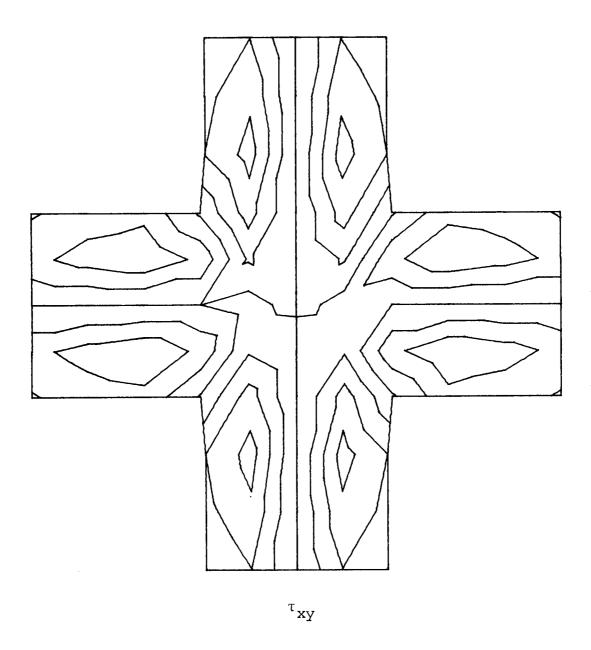


Figure (10c).-  $\tau_{xy}$  Stress Contours of Upper Flange of Composite Cross Beam Structure.

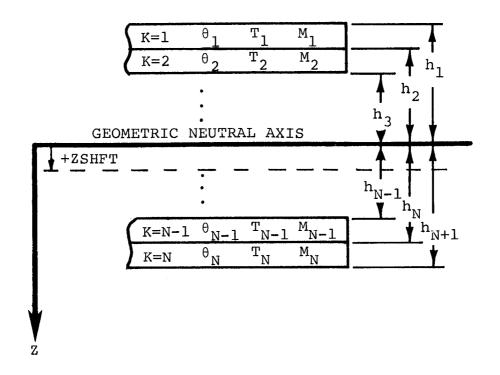


Figure (lla).- Composite Laminate Sign Convention and Construction.

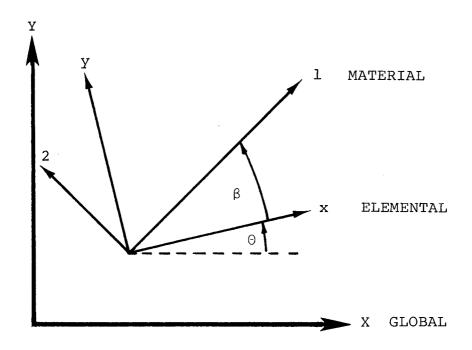


Figure (11b) .- Composite Laminate Coordinate System.

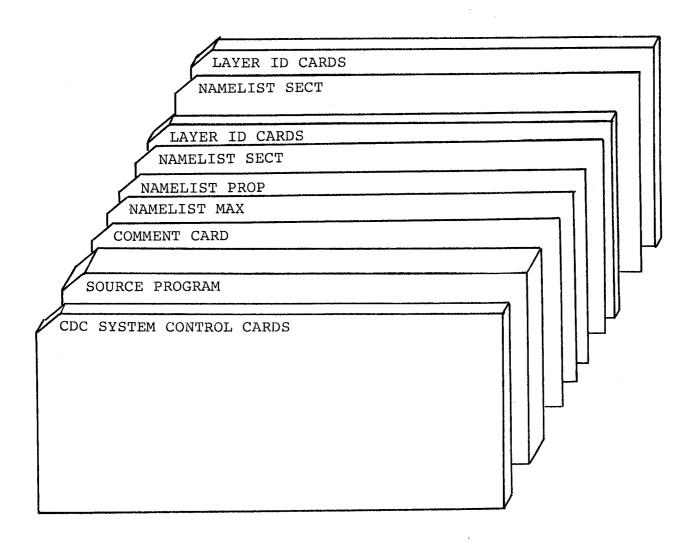


Figure (12).- Program SAT Deck Setup.

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The authors are employ	yed by the Struc	tures Lab	oratory, USART	ΓL (AVRADCOM).	
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